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| S7 | 47 | @ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and calibrat\$3 and (measur\$3 or measurement) and model\$3 and memory | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON · | 2007/08/28 13:48 |
| S9 | 103 | S8 and (dynamical\$2 with reconfigurable with module) | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 13:55 |
| S10 | 97 | S9 and interface | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 13:50 |
| S11 | 203481 | @ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and server and target communication and module and memory | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:02 |

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| S12 | 103 | S11 and (dynamical\$2 with reconfigurable with module) | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 13:55 |
| S13 | 203448 | @ad<"20031110" and (simulat\$3 with robot) and animat\$3 and server and target communication and module and memory | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 13:57 |
| S14 | 103 | S13 and (dynamical\$2 with reconfigurable with module) | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:03 |
| . S15 | 1157 | @ad<"20031110" and (simulat\$3 with robot) | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:01 |
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| S21 | 118 | S17 and model\$3 | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:03 |

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| S23 | 363 | @ad<"20031110" and (simulat\$3 and (control with system) and animat\$3 and ("700"/\$ or "702"/\$)) | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:02 |
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| S33 | 81 | @ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and server and target and communication and module and memory | US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB | OR | ON | 2007/08/28 16:16 |
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